

Awards 2025

The

AIRoV Best Paper Award 2025

was split and awarded to the papers

Improving 2D-3D Dense Correspondences with Diffusion Models for 6D Object Pose Estimation

by

Peter Hönig, Stefan Thalhammer, and Markus Vincze

and

Unsupervised Learning of Effective Actions in Robotics

by

Marko Zaric, Jakob Hollenstein, Justus Piater, and Erwan Renaudo.

Selection Process:

All workshop organizers have been asked to nominate one of their accepted papers. In total, five papers have been nominated in this way. The prize committee carefully reviewed these candidate papers, where co-authors of nominated papers abstained from voting for their papers. In this way, the committee came up with a draw, finally deciding to split the AIRoV Best Paper Award 2024.